

The Emergence, Motion, and Disappearance of Magnetic Null Points

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Introduction

- ▶ Magnetic reconnection frequently occurs at and around null points: locations where the magnetic field strength equals zero
- ▶ Models of reconnection often assume symmetry such that the magnetic null point coincides with a flow stagnation point
- ▶ However, reconnection in nature and the laboratory is typically asymmetric (e.g., Cassak & Shay 2007; Murphy et al. 2010)
- ▶ Simulations of reconnection with asymmetry typically show a gap between the null and stagnation points
 - ▶ Consequently, there are often non-ideal flows across null points (e.g., Oka et al. 2008; Murphy 2010; Wyper & Jain 2013)
- ▶ In this poster, we:
 - ▶ Derive an exact expression for the 3D motion of null points
 - ▶ Discuss how non-ideal effects lead to flows across null points
 - ▶ Discuss the appearance and disappearance of null points
 - ▶ Show that an expression for the motion of a separator cannot be derived using solely local quantities

Definitions

- ▶ We define $\mathbf{x}_n(t)$ as the time-dependent position of an isolated null point. By definition,

$$\mathbf{B}(\mathbf{x}_n) \equiv 0 \quad (1)$$

- ▶ We define \mathbf{U} as the velocity of this null point

$$\mathbf{U} \equiv \frac{d\mathbf{x}_n}{dt} \quad (2)$$

- ▶ The Jacobian matrix of the magnetic field evaluated at the null point is given by

$$\mathbf{M} \equiv \begin{pmatrix} \partial_x B_x & \partial_y B_x & \partial_z B_x \\ \partial_x B_y & \partial_y B_y & \partial_z B_y \\ \partial_x B_z & \partial_y B_z & \partial_z B_z \end{pmatrix}_{\mathbf{x}_n} \quad (3)$$

The local magnetic field structure near the null is given by $\mathbf{B} = \mathbf{M} \cdot \mathbf{r}$ where \mathbf{r} is the position vector relative to the null.

We derive an expression for the motion of a null point in an arbitrary time-varying vector field with smooth derivatives

- ▶ First we take the derivative of the magnetic field following the motion of the magnetic field null,

$$\left. \frac{\partial \mathbf{B}}{\partial t} \right|_{\mathbf{x}_n} + (\mathbf{U} \cdot \nabla) \mathbf{B} \Big|_{\mathbf{x}_n} = 0 \quad (4)$$

The RHS equals zero because the magnetic field will not change from zero as we follow the null point.

- ▶ By solving for \mathbf{U} in Eq. 4, we arrive at the exact relation

$$\mathbf{U} = -\mathbf{M}^{-1} \left. \frac{\partial \mathbf{B}}{\partial t} \right|_{\mathbf{x}_n} \quad (5)$$

- ▶ A null is structurally stable and will continue to exist when \mathbf{M} is non-singular and structurally unstable when \mathbf{M} is singular.
- ▶ Geometric information about the magnetic field is contained within \mathbf{M} . It is easier to change the position of a root of a function by a vertical shift if the slope is shallow.

We derive an exact expression for the rate of motion of an isolated magnetic null point independent of Ohm's law

- ▶ Faraday's law is given exactly by

$$\frac{\partial \mathbf{B}}{\partial t} = -\nabla \times \mathbf{E} \quad (6)$$

- ▶ By applying Faraday's law to Eq. 5, we arrive at

$$\mathbf{U} = \mathbf{M}^{-1} \nabla \times \mathbf{E}|_{x_n} \quad (7)$$

This expression is independent of choice of Ohm's law, and does not even require the existence of an Ohm's law.

In resistive MHD, null point motion results from a combination of advection by the bulk plasma flow and resistive diffusion of the magnetic field

- ▶ Next, we apply the resistive MHD Ohm's law,

$$\mathbf{E} + \mathbf{V} \times \mathbf{B} = \eta \mathbf{J} \quad (8)$$

where we assume the resistivity to be uniform.

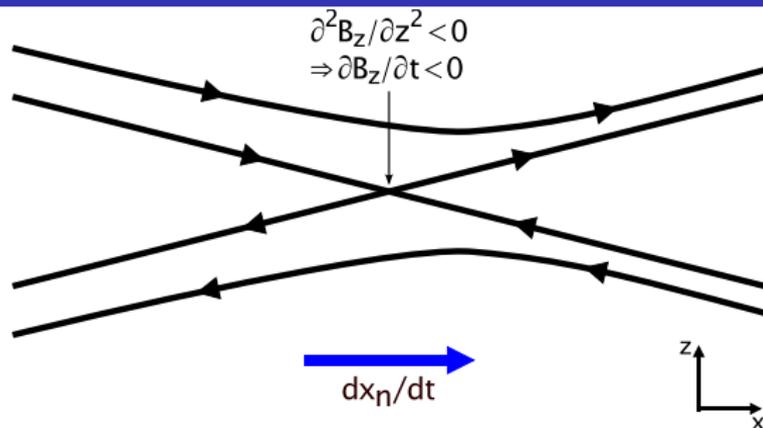
- ▶ The expression for the rate of motion of a null point becomes

$$\mathbf{U} = \mathbf{V} - \eta \mathbf{M}^{-1} \nabla^2 \mathbf{B} \quad (9)$$

where all quantities are evaluated at the magnetic null point.

- ▶ The first term on the RHS represents the bulk plasma flow velocity at the null point.
- ▶ The second term on the RHS represents motion of the null point via resistive diffusion.

Murphy (2010): X-line retreat in resistive MHD



- ▶ X-line retreat in 1-D occurs due to a combination of bulk plasma flow along the outflow direction and diffusion of the normal component of the magnetic field:

$$\frac{dx_n}{dt} = V_x(x_n) - \eta \left[\frac{\frac{\partial^2 B_z}{\partial x^2} + \frac{\partial^2 B_z}{\partial z^2}}{\frac{\partial B_z}{\partial x}} \right]_{x_n} \quad (10)$$

- ▶ $B_z < 0$ both above and below the X-line. Diffusion of B_z causes the current X-line position to have negative B_z at a slightly later time. The X-line therefore moves to the right.

Additional effects in the generalized Ohm's law

- ▶ Additional terms in the generalized Ohm's law can be incorporated by re-evaluating Eq. 7.
- ▶ For example, if we choose our Ohm's law to be

$$\mathbf{E} + \mathbf{V}_i \times \mathbf{B} = \eta \mathbf{J} + \frac{\mathbf{J} \times \mathbf{B}}{n_e e} - \frac{\nabla P_e}{n_e e} \quad (11)$$

with $\mathbf{J} = n_e e (\mathbf{V}_i - \mathbf{V}_e)$, then Eq. 7 becomes

$$\mathbf{U} = \mathbf{V}_e - \eta \mathbf{M}^{-1} \nabla^2 \mathbf{B} + \mathbf{M}^{-1} \left(\frac{\nabla n_e \times \nabla P_e}{n_e^2 e} \right) \quad (12)$$

Again, all terms are evaluated at the null point.

- ▶ The relevant plasma velocity becomes the electron velocity rather than the bulk plasma velocity.
- ▶ The last term corresponds to the Biermann battery.

Appearance and disappearance of nulls

- ▶ Much of the work on the appearance and disappearance of nulls uses bifurcation theory and topological analysis (e.g., Priest, Lonie, & Titov 1996).
- ▶ Null points must come in and out of existence through diffusion or other non-ideal effects: therefore, non-ideal effects must be included for a self-consistent description of the appearance and disappearance of nulls.
- ▶ Nulls are degenerate at the instant when they appear or disappear before bifurcating into a null-null pair.
- ▶ The Jacobian matrix of the null is singular, so the velocity of separation (convergence) is instantaneously infinite at the beginning (end) of a null's existence.

Can we perform a similar local analysis to describe the motion of separators?

- ▶ A separator is a magnetic field line connecting two null points
 - ▶ These are often important locations for reconnection.
- ▶ The locations of separators change as the plasma evolves.
 - ▶ If the evolution is ideal, then the motion of the separator will be given by its field line velocity.
 - ▶ If the evolution is non-ideal, then topology changes must be considered.
- ▶ Suppose that there is non-ideal behavior along one segment of the separator but not along the rest of it. At a slightly later time, the field line in the ideally evolving region will in general no longer be the separator even though the evolution was locally ideal.
 - ▶ Therefore, it is not possible to find an exact expression describing separator motion based solely on local parameters.
 - ▶ However, a global approach could lead to an exact expression by taking into account connectivity changes along the separator as well as motion of its endpoints.

Conclusions

- ▶ We derive an exact expression for the motion of a magnetic null point that depends solely on parameters evaluated at the null. This expression can be applied for arbitrary Ohm's law
- ▶ In resistive MHD, the position of a null point can change via bulk plasma flow or resistive diffusion of the magnetic field.
- ▶ Magnetic null points must diffuse in and out of existence through non-ideal effects. Upon formation, a new null is degenerate before bifurcating into a null-null pair. These new nulls have an instantaneously infinite velocity of separation.
- ▶ An expression for the motion of separators must include information on plasma motion and connectivity changes along its entire length.

Puns about computational magnetohydrodynamics

- ▶ This topic is pretty narrow, so we may have to allow for some divergence error.
- ▶ Fortunately, the standards for these puns are pretty Lax.
- ▶ Momentum transfer between ions and neutrals, however, is kind of a drag.
- ▶ I could have put in more puns, but I'm being conservative.
- ▶ Thank you for converging at my poster. I am glad we did not get a null result.
- ▶ And remember, if you ever need someone to numerically solve a system of vector partial differential equations that you're embarrassed about not being able to solve analytically, I can be discrete.